

# I&C 101

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# Agenda

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## I&C 101

- Design drawings
- Hardware
- Software
- PIDs

**Why I&C?**

# My I&C story



***Starting up the Woodland Davis WTP in 2016***



***Lahaina WWRF commissioning in 2022***



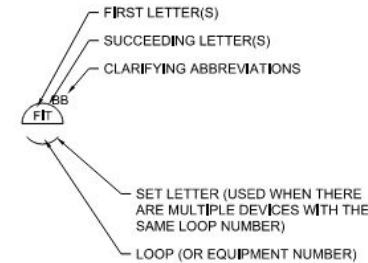
# Design drawings

# P&IDs – When in doubt, check the P&ID!

- Refer to project specific legend sheet
- If it's not captured correctly on the P&ID then don't expect it to get built correctly
- Shows
  - Equipment
  - Manufacturer provided equipment & cables
  - Tags
  - Power requirements
  - IO signals
  - Flow path

## INSTRUMENT IDENTIFICATION

### EXAMPLE SYMBOLS



### SIGNAL INTERFACES

▲	ANALOG INPUT	WHERE X=
▼	ANALOG OUTPUT	A ■ ALARM
Δ <sub>x</sub>	DISCRETE INPUT	H ■ MAINTAINED
▽ <sub>x</sub>	DISCRETE OUTPUT	M ■ MOMENTARY
		S ■ STATUS

### GENERAL INSTRUMENT OR FUNCTIONAL SYMBOLS

○	FIELD MOUNTED
○ ---	REAR-OF-PANEL MOUNTED (OPERATOR INACCESSIBLE)

### INSTRUMENT IDENTIFICATION LETTERS TABLE

LETTER	FIRST-LETTER		SUCCEEDING-LETTERS		
	PROCESS OR INITIATING VARIABLE	MODIFIER	READOUT OR PASSIVE FUNCTION	OUTPUT FUNCTION	MODIFIER
A	ANALYSIS (+)		ALARM		
B	BURNER, COMBUSTION		USER'S CHOICE (*)	USER'S CHOICE (*)	USER'S CHOICE (*)
C	USER'S CHOICE (*)			CONTROL	
D	DENSITY (S.G)	DIFFERENTIAL			
E	VOLTAGE		PRIMARY ELEMENT, SENSOR		
F	FLOW RATE	RATIO (FRACTION)			
G	USER'S CHOICE (*)		GLASS, GAUGE VIEWING DEVICE	GATE	
H	HAND (MANUAL)				HIGH
I	CURRENT (ELECTRICAL)		INDICATE		
J	POWER	SCAN			
K	TIME, TIME SCHEDULE	TIME RATE OF CHANGE		CONTROL STATION	
L	LEVEL		LIGHT (PILOT)		LOW
M	MOTION	MOMENTARY			MIDDLE, INTERMEDIATE
N	TORQUE		USER'S CHOICE (*)	USER'S CHOICE (*)	USER'S CHOICE (*)
O	USER'S CHOICE (*)		ORIFICE, RESTRICTION		
P	PRESSURE, VACUUM		POINT (TEST) CONNECTION		
Q	QUANTITY	INTEGRATE, TOTALIZE			
R	RADIATION		RECORD OR PRINT		
S	SPEED, FREQUENCY	SAFETY		SWITCH	
T	TEMPERATURE			TRANSMIT	
U	MULTIVARIABLE		MULTIFUNCTION	MULTIFUNCTION	MULTIFUNCTION
V	VIBRATION, MECHANICAL ANALYSIS			VALVE, DAMPER, LOUVER	
W	WEIGHT, FORCE		WELL		
X	UNCLASSIFIED (+)	X AXIS	UNCLASSIFIED (+)	UNCLASSIFIED (+)	UNCLASSIFIED (+)
Y	EVENT, STATE OR PRESENCE	Y AXIS		RELAY, COMPUTE, CONVERT	
Z	POSITION	Z AXIS		DRIVE, ACTUATOR, UNCLASSIFIED FINAL CONTROL ELEMENT	

TABLE BASED ON THE INSTRUMENTATION, SYSTEMS, AND AUTOMATION SOCIETY (ISA) STANDARD.

(+) WHEN USED, EXPLANATION IS SHOWN ADJACENT TO INSTRUMENT SYMBOL. SEE ABBREVIATIONS AND LETTER SYMBOLS.

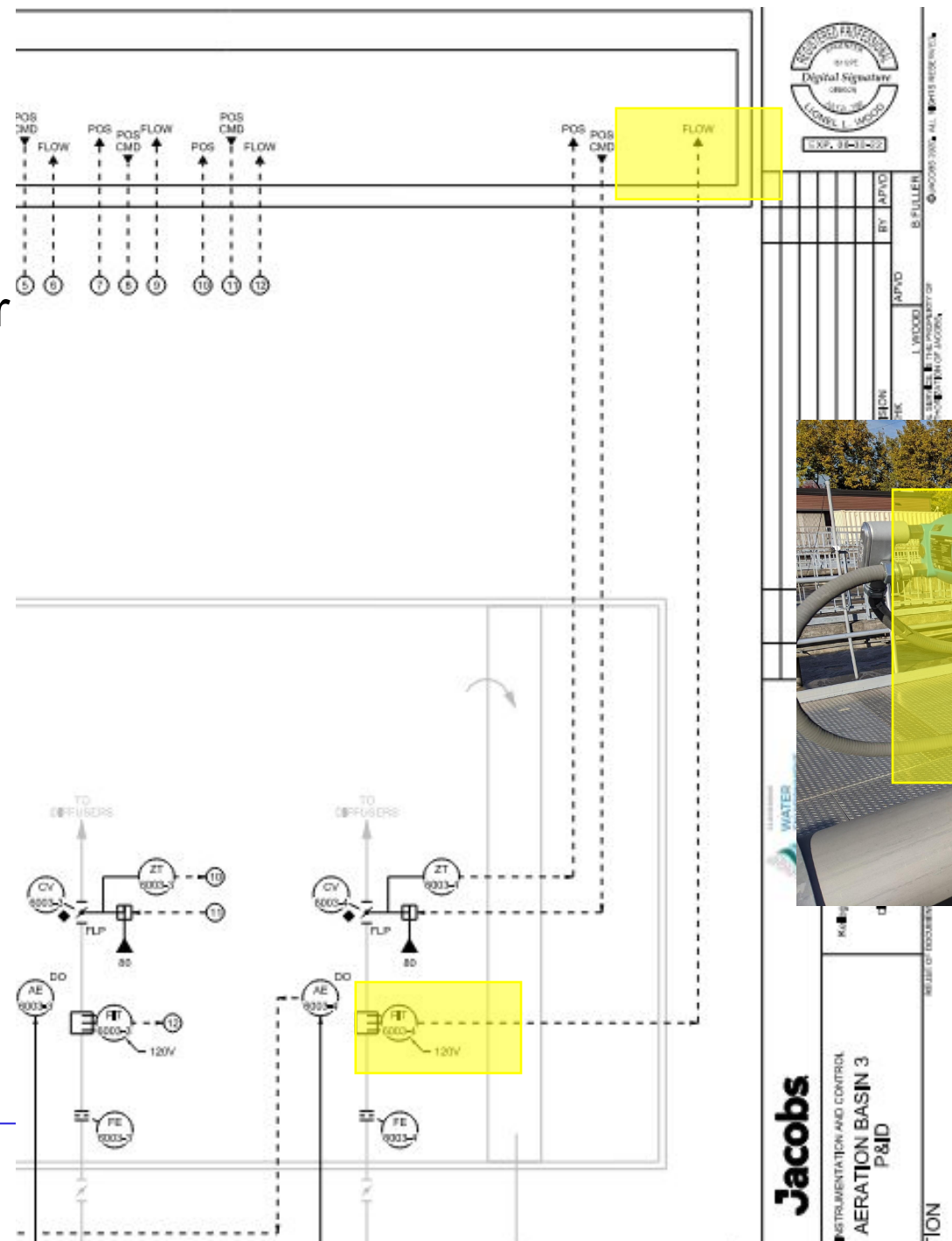
(\*) WHEN USED, DEFINE THE MEANING HERE FOR THE PROJECT

**Portion of example P&ID legend sheet**



# P&IDs

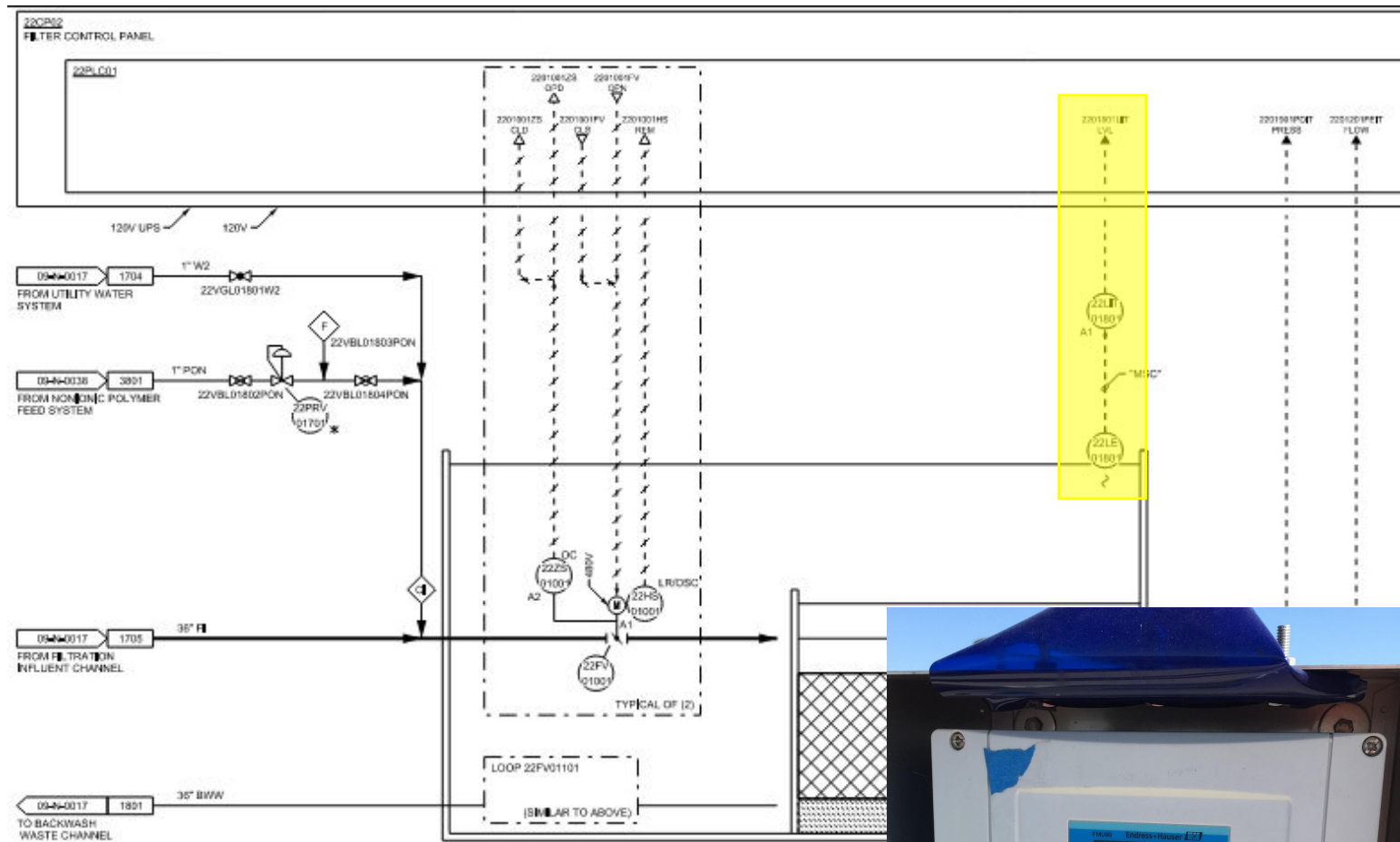
- FIT
  - Flow Indicating Transmitter



*Air flow meter*

# P&IDs

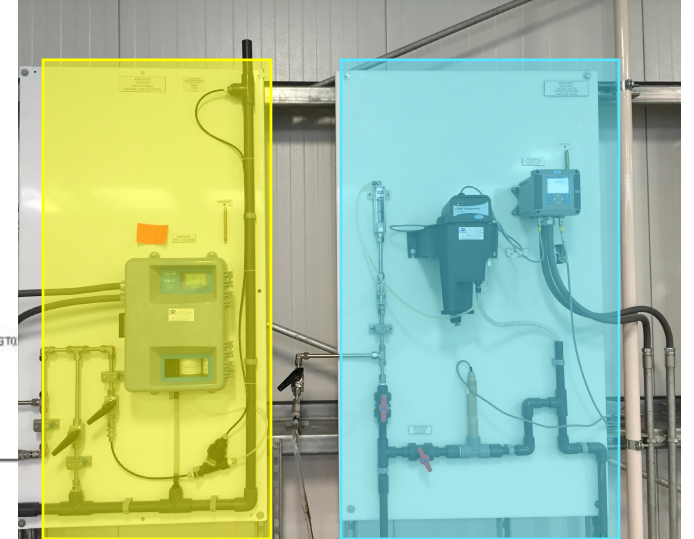
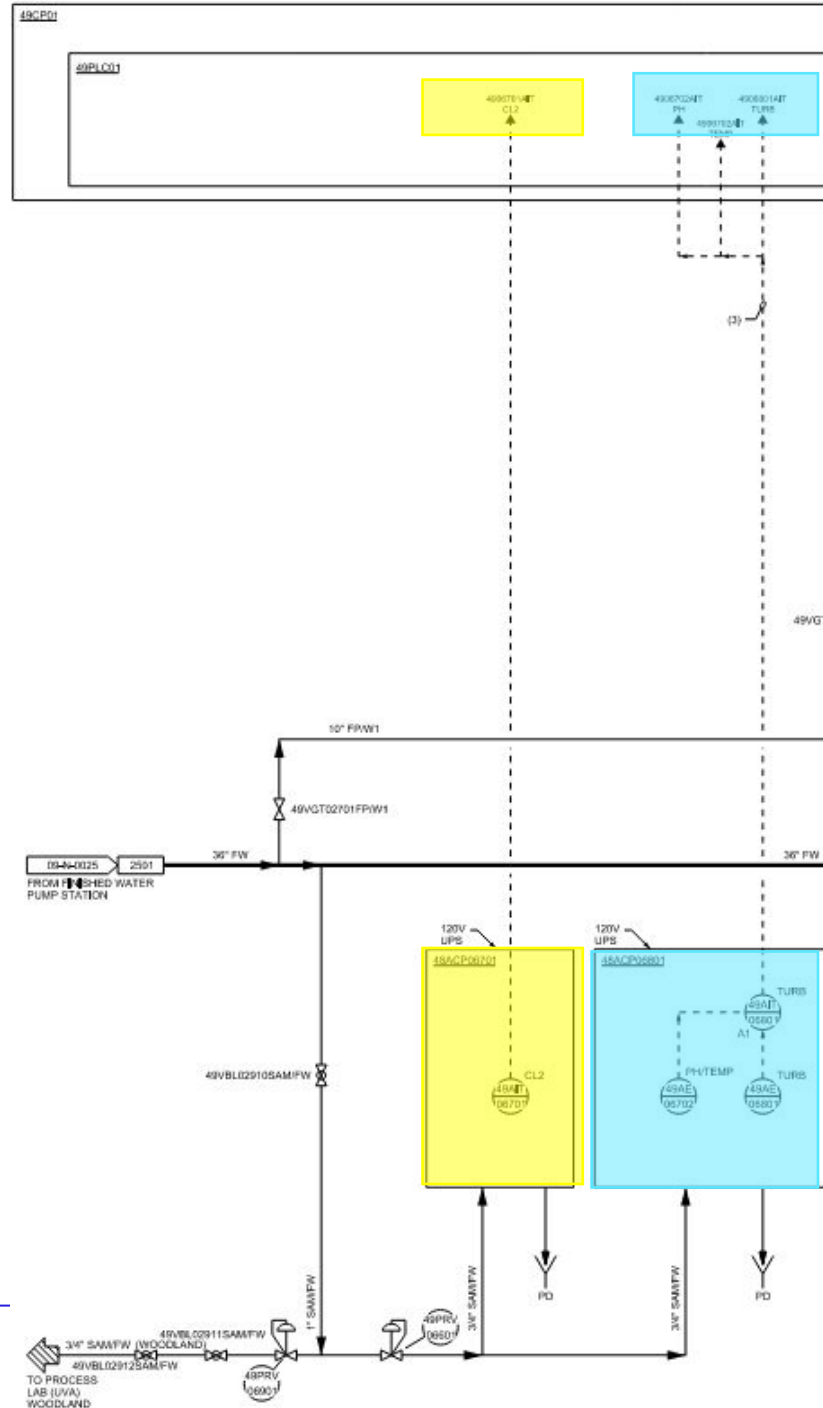
- LIT
  - Level Indicating Transmitter





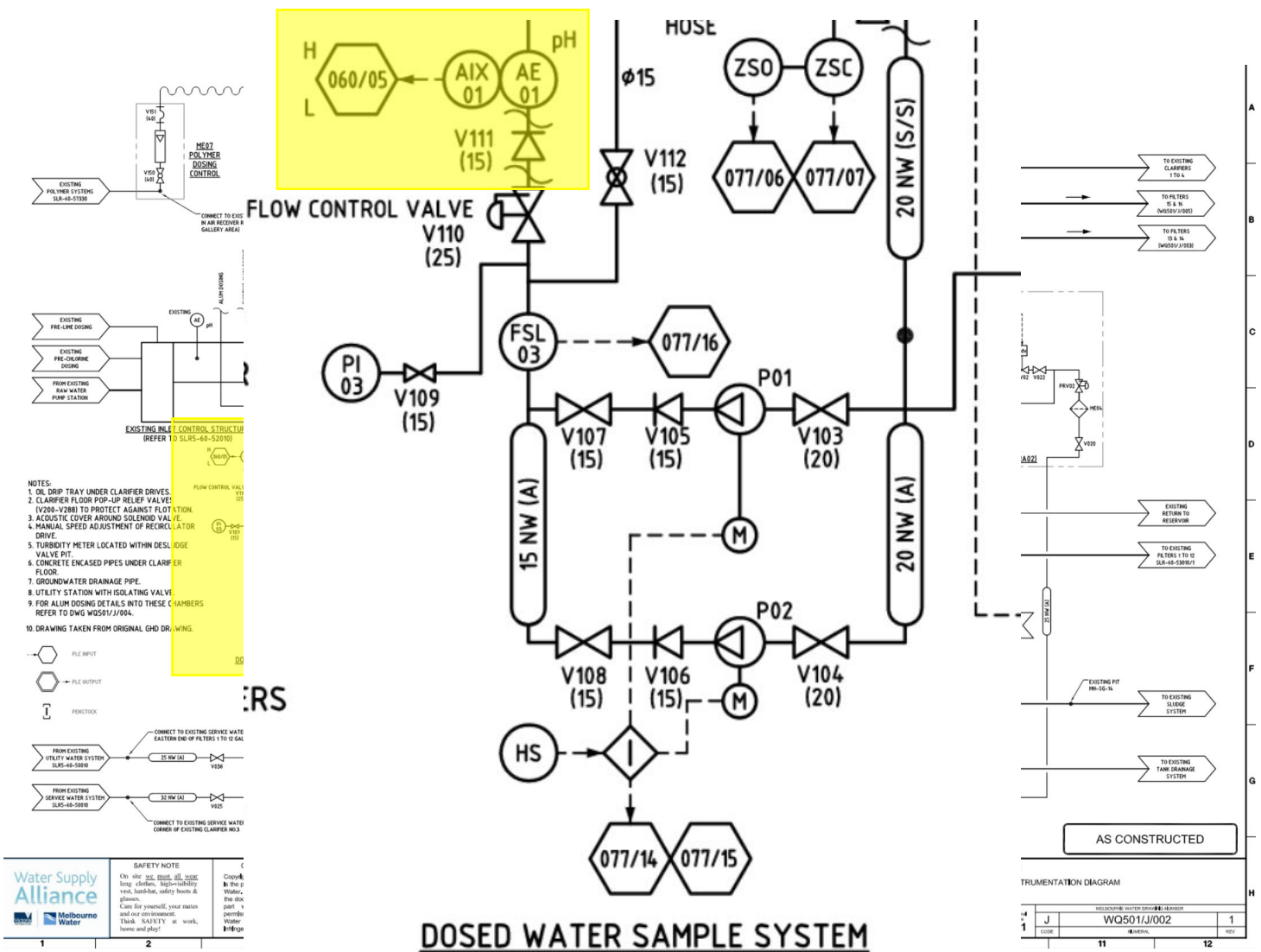
# P&IDs

- AIT
  - Analyzer Indicating Transmitter
  - Subscript for type



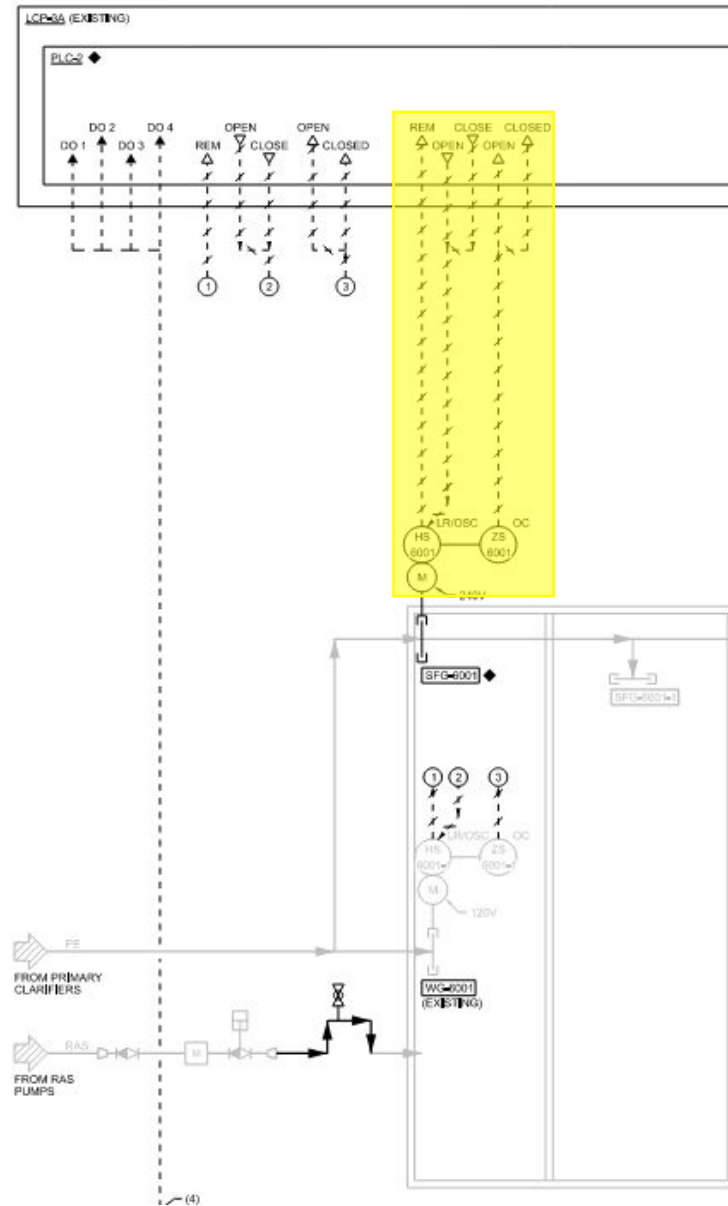
# P&IDs

- Lots of different P&ID flavors, but they all communicate critical information



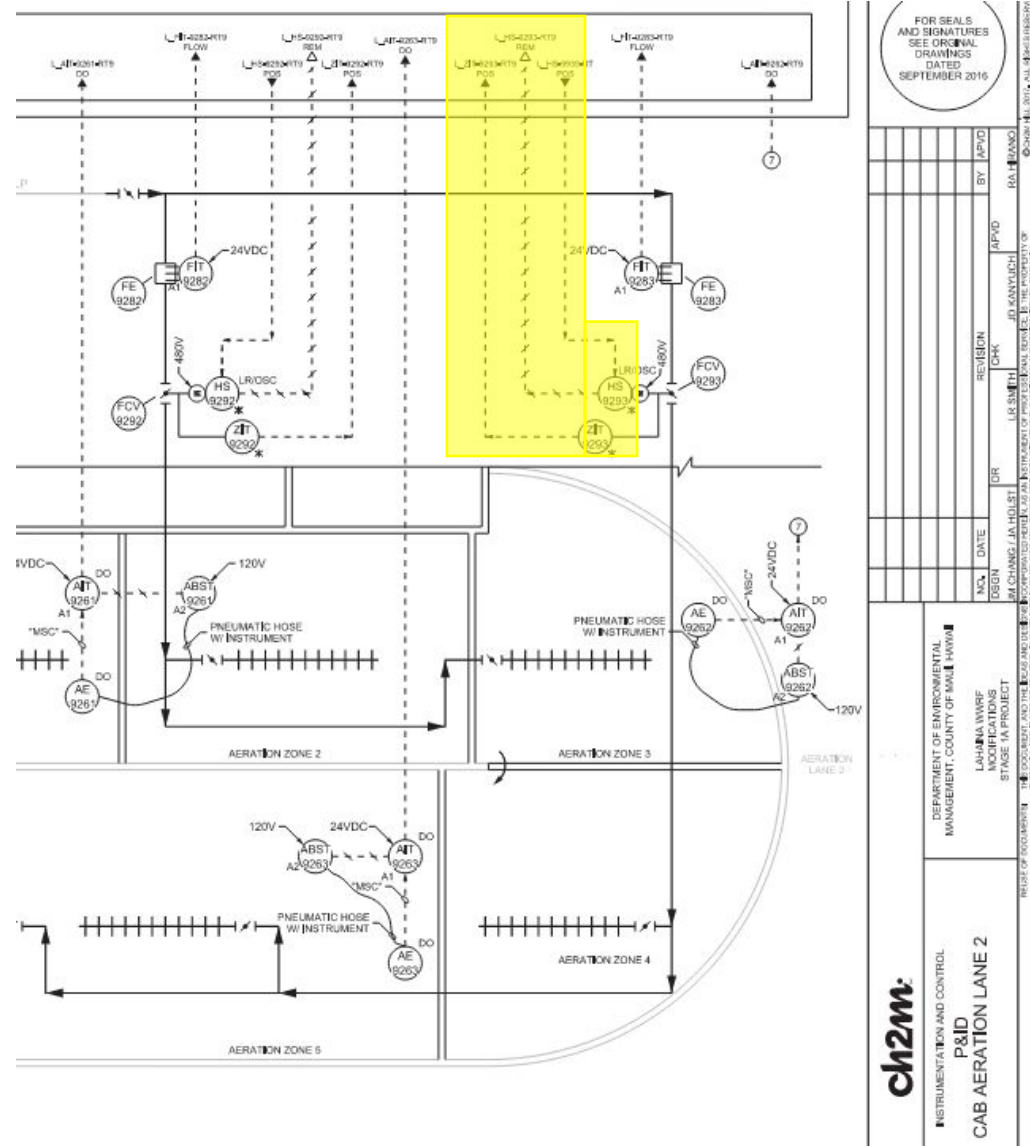
# P&IDs

- Valve/gate actuators
  - Open Close (OC)
    - Discrete open/close command and feedback



# P&IDs

- Valve/gate actuators
  - Modulating
    - Analog position command and feedback

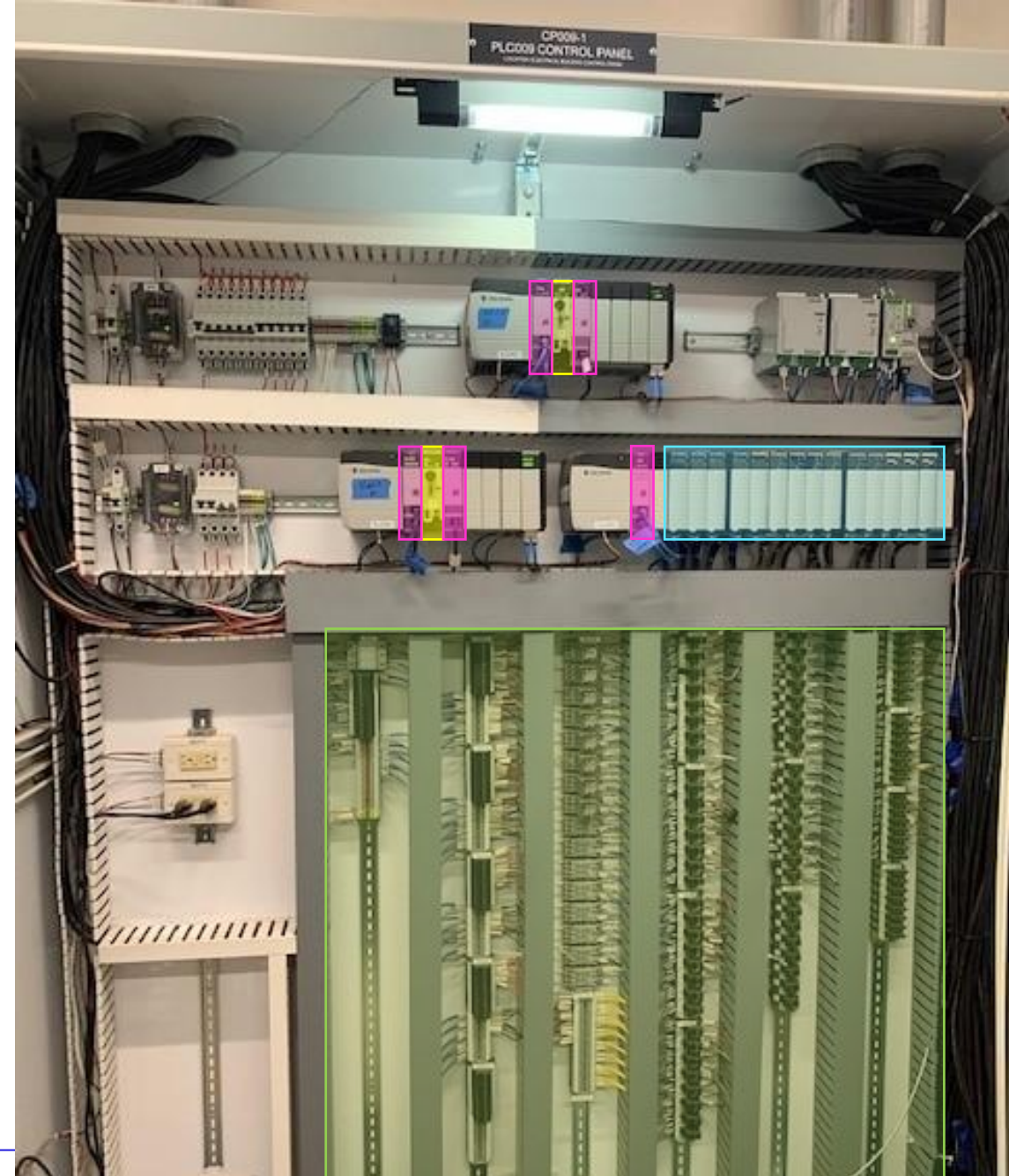




# Hardware and associated drawings

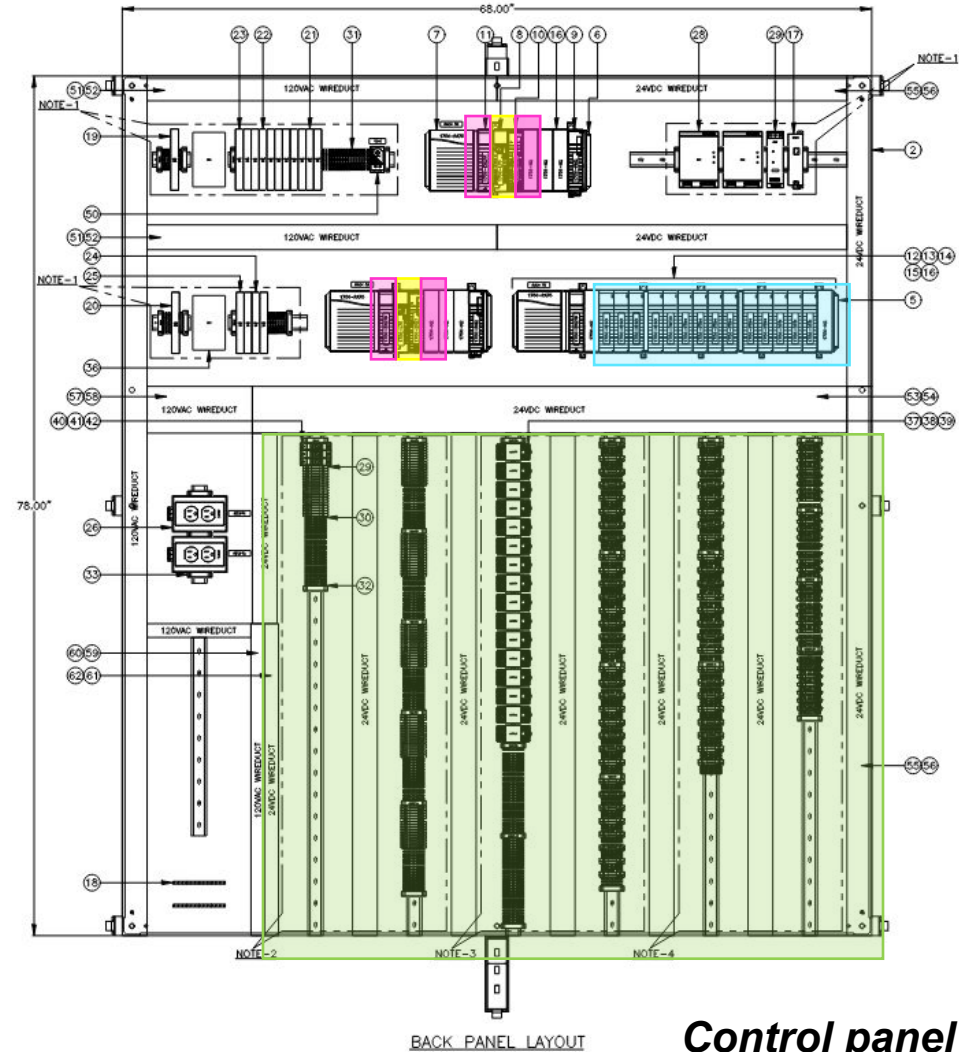
# Control Panels

- **PLC** (Programmable Logic Controller)
  - Processor programmed to control equipment
    - Redundant PLCs in photo
- **Communication cards**
  - Connects PLC to SCADA
  - Connects remote IO racks
- **IO cards** (Input/Output)
  - Receive signals from terminal blocks and sends to PLC
- **Terminal blocks**
  - Where wires to/from the field are landed

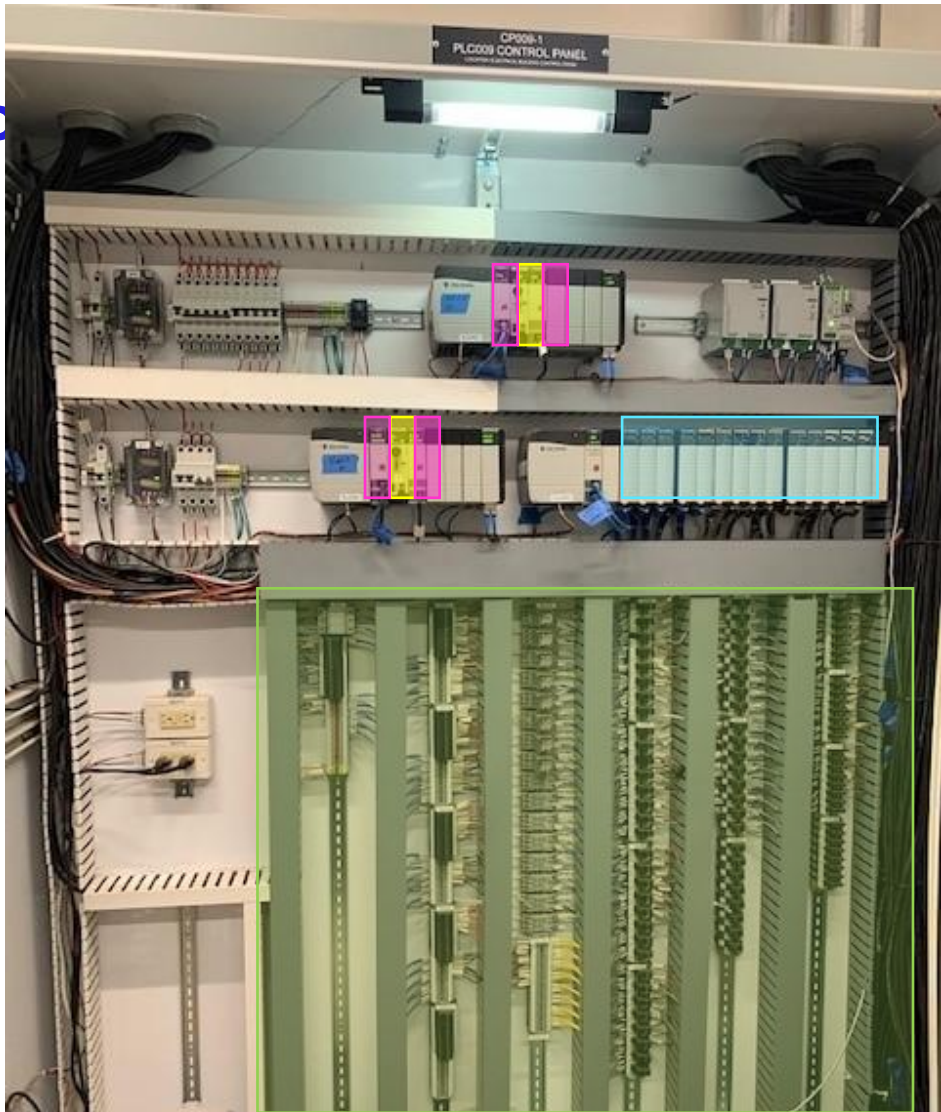




# Control Panels – Where do the IO signals go

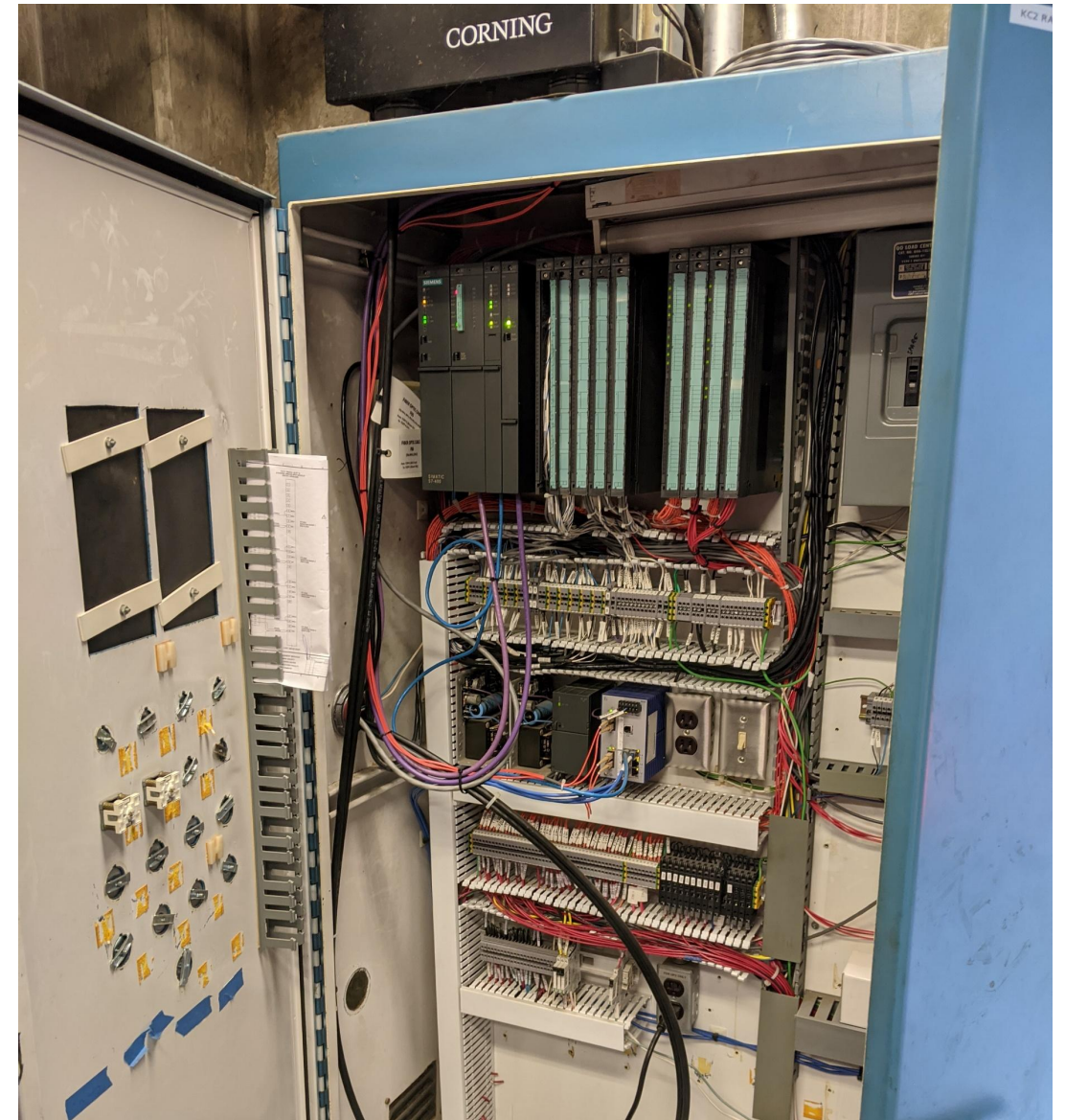


Control panel drawing and photo



# Control panels

- Common PLC manufacturers
  - Allen-Bradley
  - Siemens
  - Schneider Electric (Modicon)
  - Honeywell
  - Emerson
- Common communication protocols
  - EthernetIP
  - Modbus
  - Profibus
  - HART

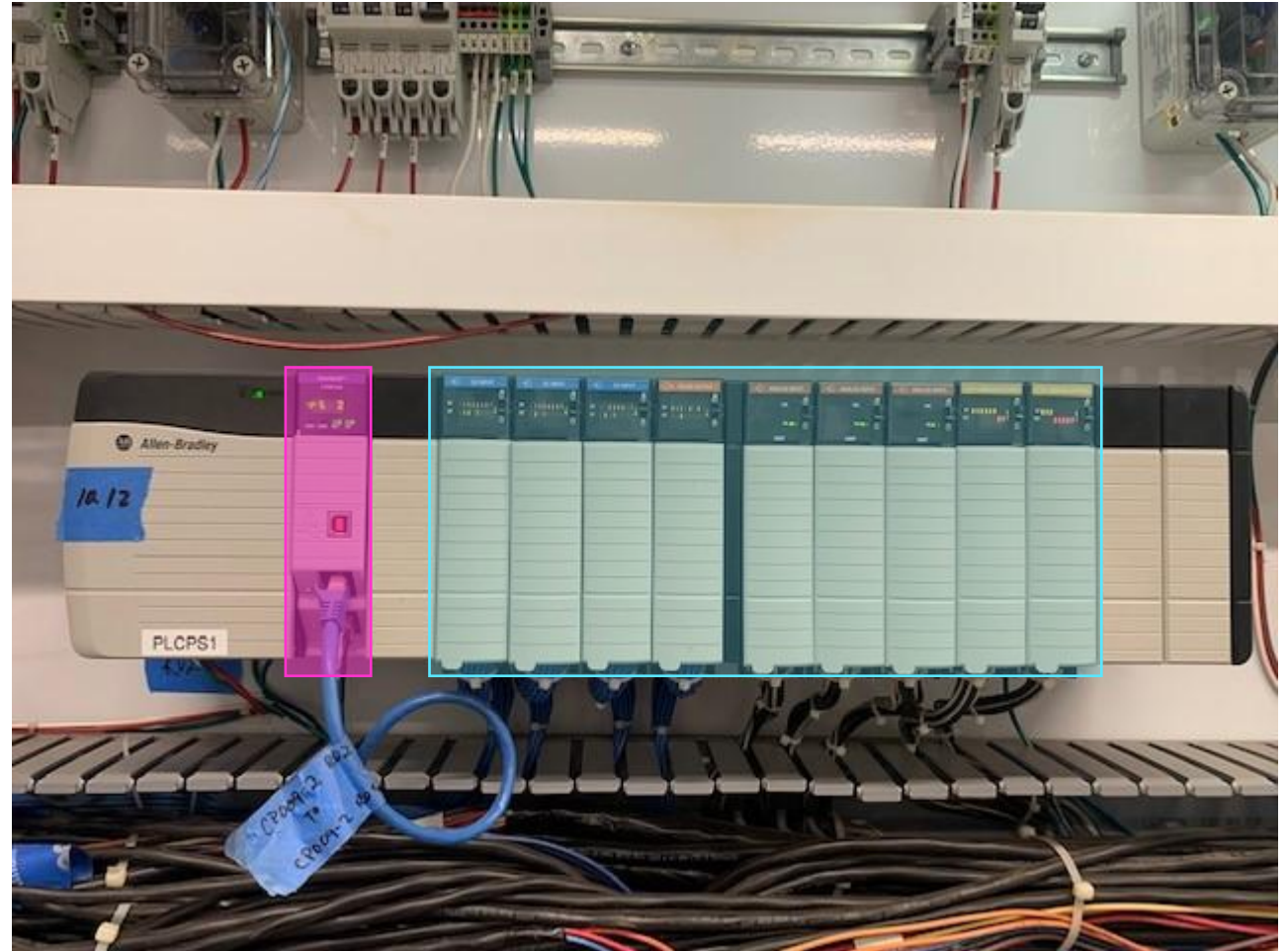


***Siemens PLC hardware (prior to upgrade)***



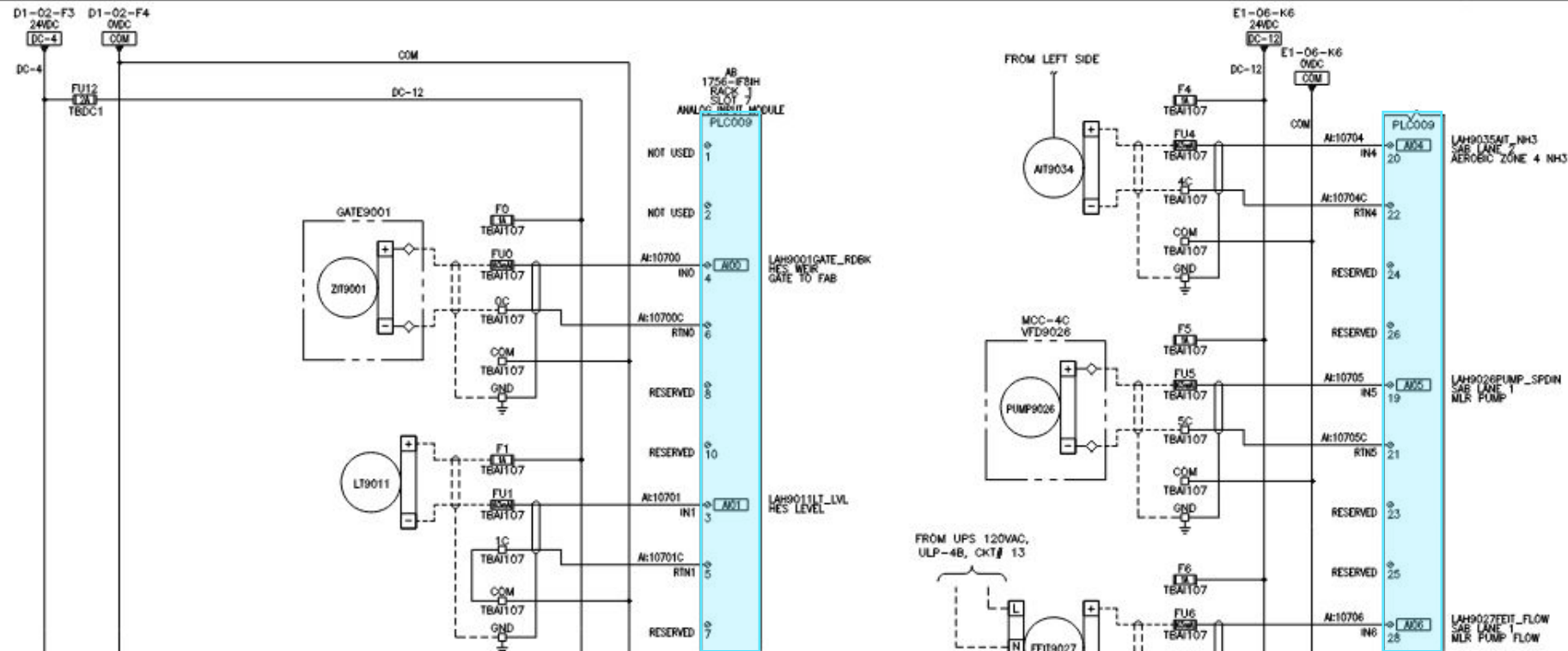
# Types of IO

- Discrete Input (DI)
  - Input from field to PLC
  - 0 or 1
  - Ex: Open valve feedback where 1 = Opened
- Discrete Output (DO)
  - Output from PLC to field
  - 0 or 1
  - Ex: Open valve command where 1 = Open
- Analog Input (AI)
  - Input from field to PLC
  - 4 to 20 mA signal scaled to process value
  - Ex: Flow value
- Analog Output (AO)
  - Output from field to PLC
  - Process value scaled to 4 to 20 mA signal
  - Ex: Pump speed command



***Allen-Bradley IO cards***

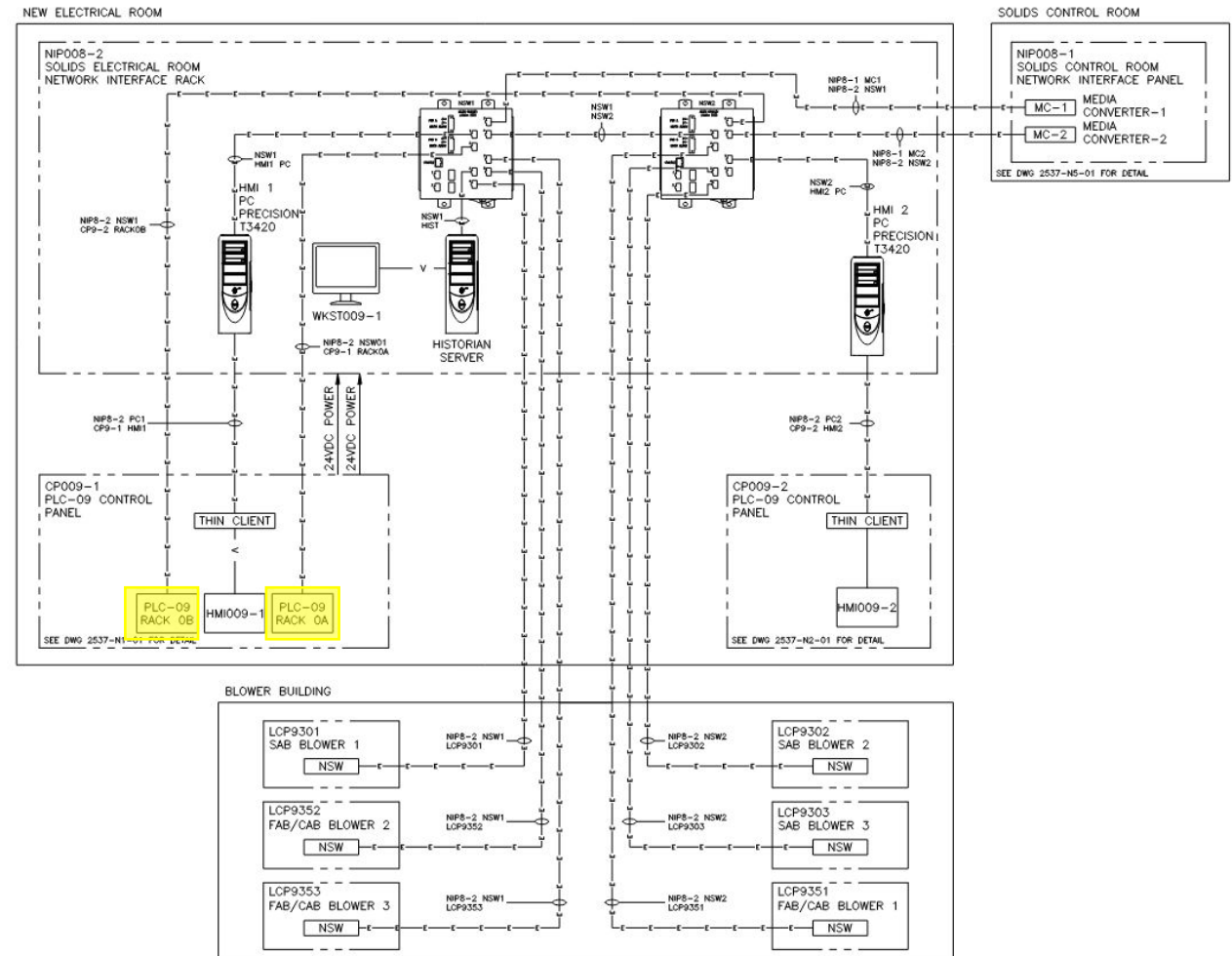
# Wiring diagrams – How are the IO signals wired from the field to the control panel?



**Analog Input (AI) wiring diagram – shows where field wires land on terminal blocks and wiring from terminal block to AI IO card**

# Network block diagrams – How does the control system communicate?

- PLC network stand alone and protected by firewall
  - Secure remote access via multi-factor authentication



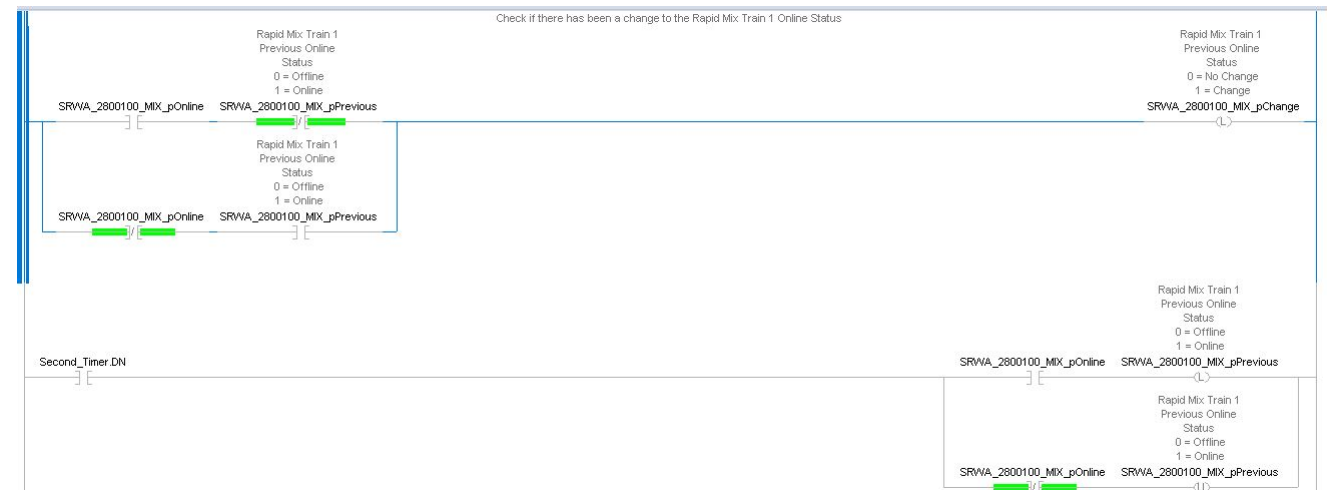
*Network block diagram showing connectivity between master PLC, HMI, SCADA and blower F*

# Software



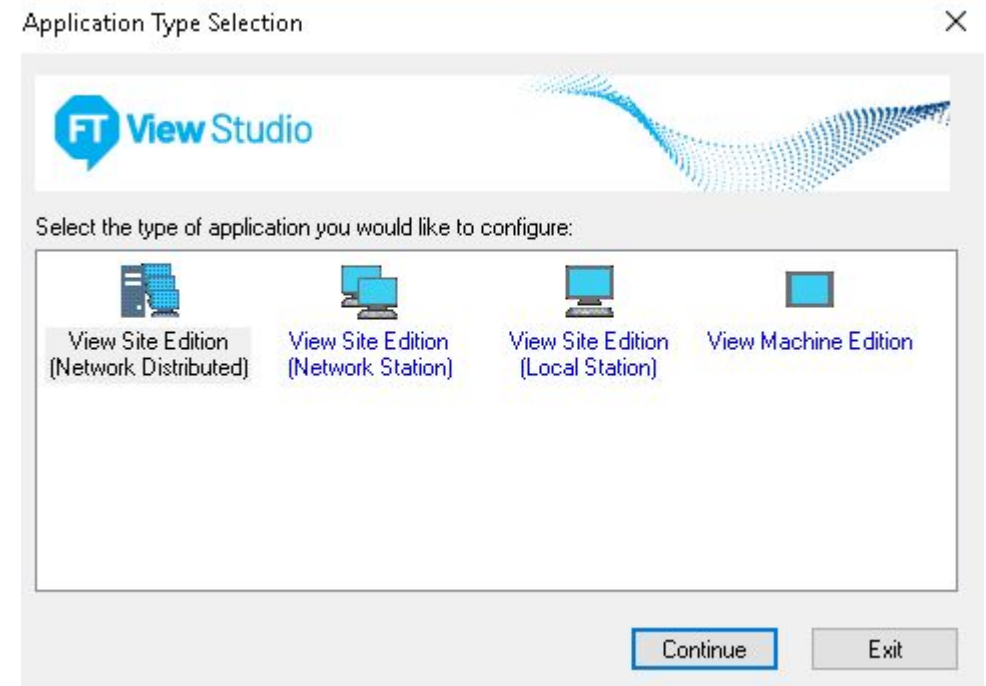
# PLC

- Programmable Logic Controllers (PLCs)
  - Software to program how the plant is controlled
- Commonly used software used
  - Studio 5000 by Rockwell for Allen-Bradley PLCs
  - TIA Portal for Siemens PLCs
  - Concept for Modicon
- PLC programming languages
  - Ladder diagram
  - Function block diagram
  - Sequential function chart
  - Structured text



# SCADA

- Supervisory Control and Data Acquisition
  - Plant wide control
  - Displays equipment status, process variables
  - Allows operations to change setpoints, start/stop equipment
- Common software used
  - Factorytalk by Rockwell
  - Ignition by Inductive Automation
  - System Platform by AVEVA (formally Wonderware)
  - Cimplicity by GE
- Alarming
  - Notifies operations of equipment faults, process variables too high or too low, communication failures etc
  - Typically, at SCADA and via text message/dial out



## 23

2025

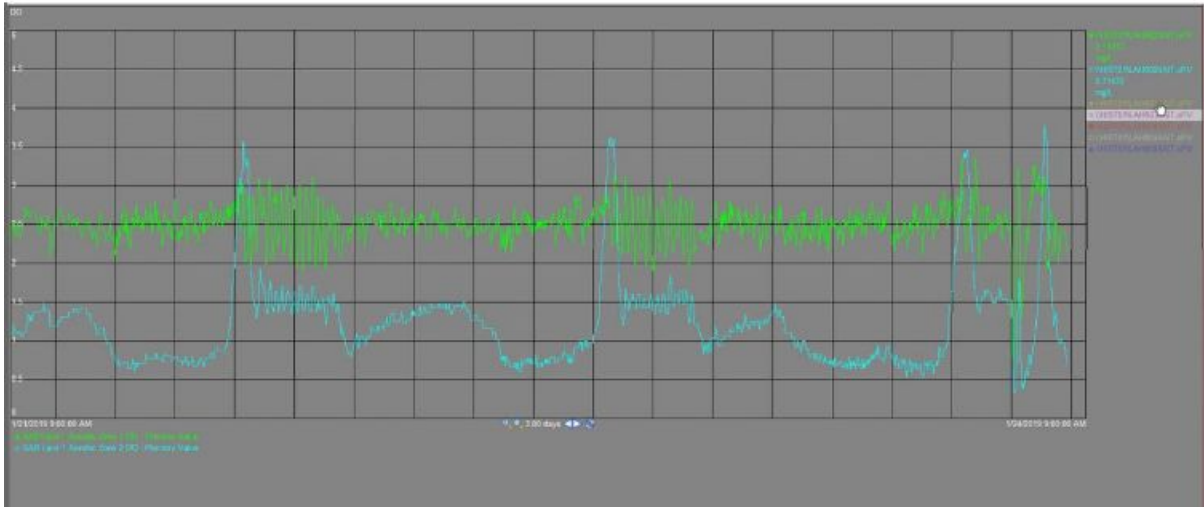
# HMI

- Human Machine Interface
  - Control of particular process or facility
  - Displays equipment status, process variables
  - Allows operations to change setpoints, start/stop equipment
  - Typically provided with vendor packages



# Historian

- Configured to store historical values relevant to plant operation
- Data accessible on PLC network via trending, reports and data exports



Start Time	8/2/2022 8:30		
End Time	8/6/2022 8:30		
		LAH9001FI.oPV	LAH9000FI.oPV
		Flow to FAB/CAB - Calculated Process Value	Total Plant Flow - Calculated Process Value
		MGD	MGD
8:30:00 AM	02-Aug-22 08:30:00	5.26	5.31
8:35:00 AM	02-Aug-22 08:35:00	5.56	5.31
8:40:00 AM	02-Aug-22 08:40:00	6.34	5.41
8:45:00 AM	02-Aug-22 08:45:00	4.72	5.41
8:50:00 AM	02-Aug-22 08:50:00	5.70	5.41
8:55:00 AM	02-Aug-22 08:55:00	4.75	5.41
9:00:00 AM	02-Aug-22 09:00:00	6.35	5.41
9:05:00 AM	02-Aug-22 09:05:00	6.01	5.52
9:10:00 AM	02-Aug-22 09:10:00	5.32	5.62
9:15:00 AM	02-Aug-22 09:15:00	5.73	5.62



**What is a PID?**



# PID Defintion

## ■ Proportional-Integral-Derivative Controller

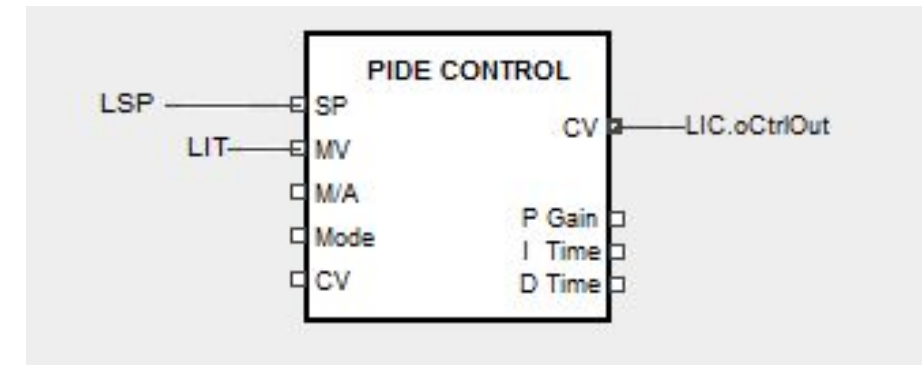
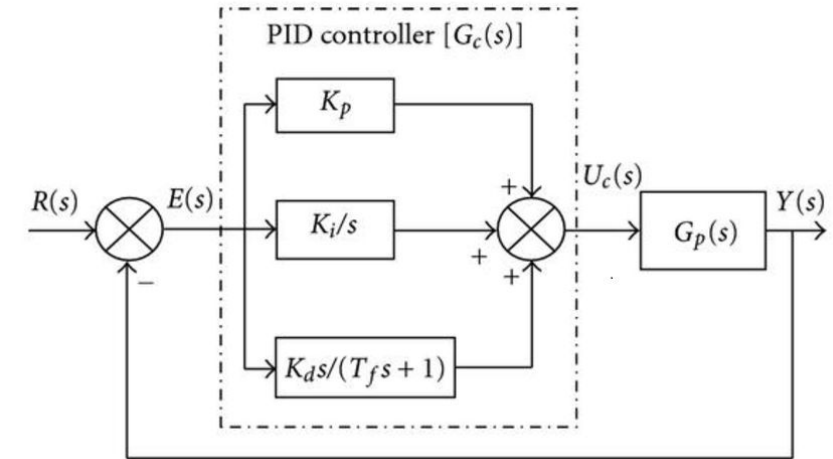
- Proportional: changes output proportional to error
- Integral: changes output according to the accumulated error
- Derivative: changes output as the rate of change of error increases

### ■ Inputs:

- Setpoint (SP)
- Measured Variable (MV) also called Process Variable (PV)
- Flow, level, pressure

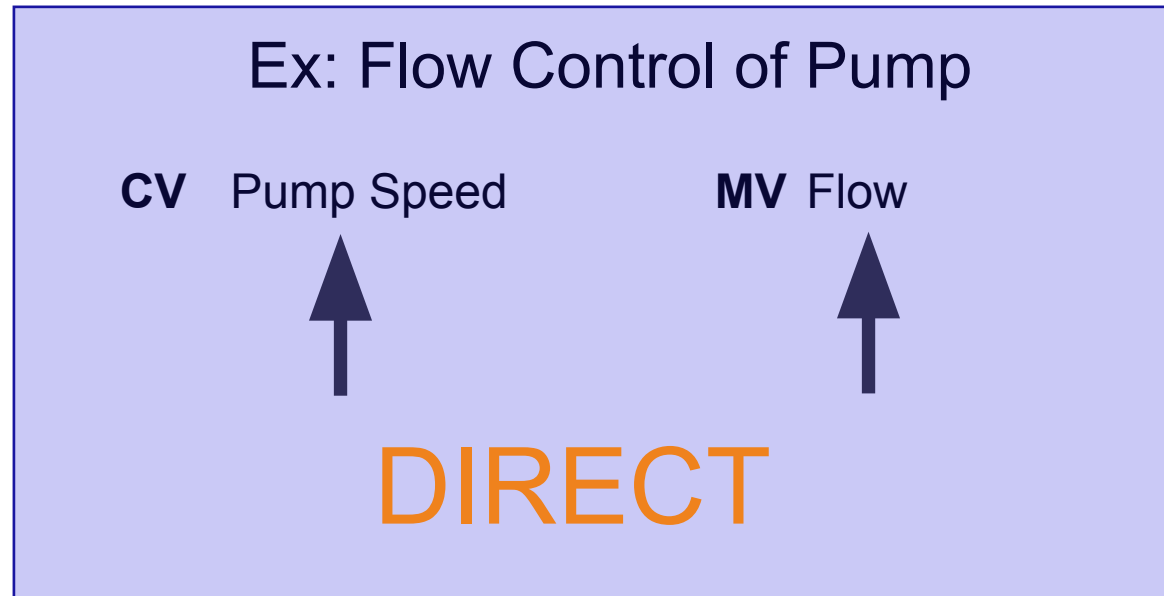
### ■ Output:

- Control Variable (CV)
- Pump speed, valve/gate position, etc.



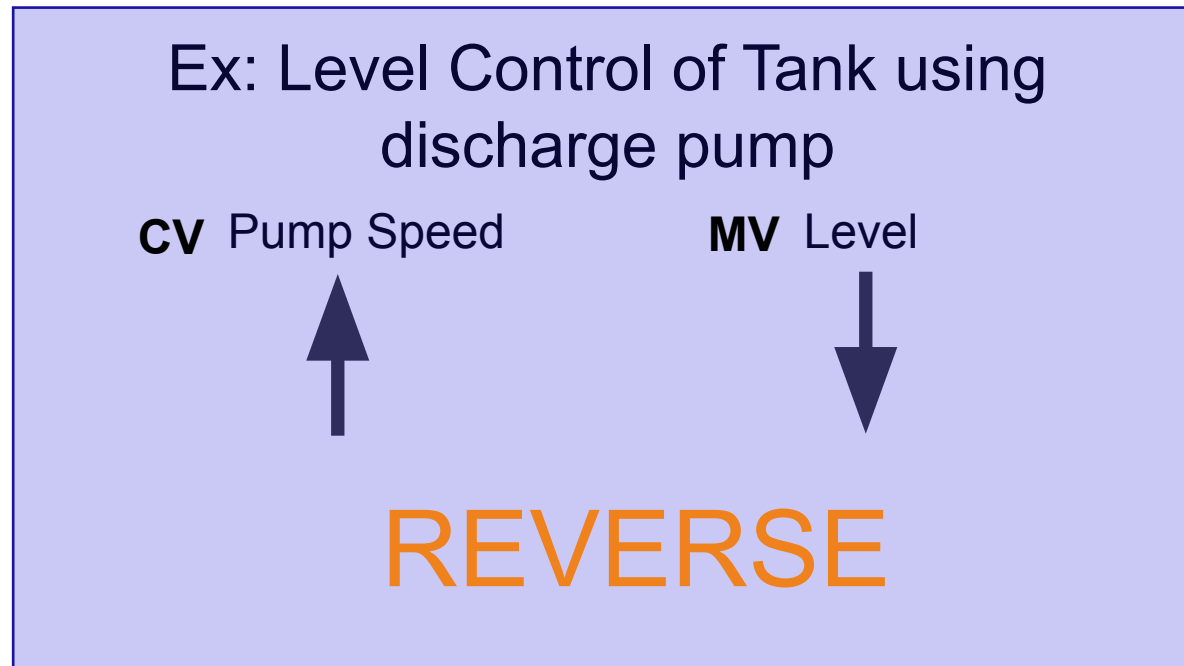
## PID Definition

- Direct Acting: Controller output increases as measured variable increases



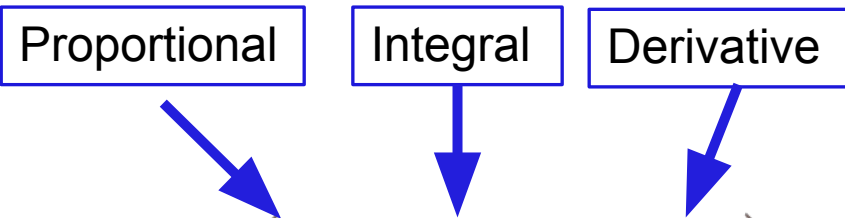
## PID Definition

- Reverse Acting: Controller output decreases as measured variable increases



# PID Equation

- Two forms of equation
  - **Dependent**
    - Controller gain effects action of all three terms (P, I and D)
  - Independent
  - Know what form your controller is using


$$CV_N = CV_{N-1} + K_C \left( E + \frac{E \Delta t}{T_I} + T_D \frac{\Delta E}{\Delta t} \right) + Bias$$

$CV_N$  = Control Variable at time step n

$CV_{N-1}$  = Control Variable at time step n-1

$K_C$  = Controller Gain

$T_I$  = Integral time constant (seconds/repeat)

$T_D$  = Derivative time constant (seconds)

$E$  = Error

$\Delta E$  = Change in Error

$\Delta t$  = Change in Time

$Bias$  = Offset for CV calculation

# Error Equation

- Calculation of Error depends on the minimum and maximum of the measured variable

$$Error = SP - MV / (Max\ MV - Min\ MV)$$

*SP* = Setpoint

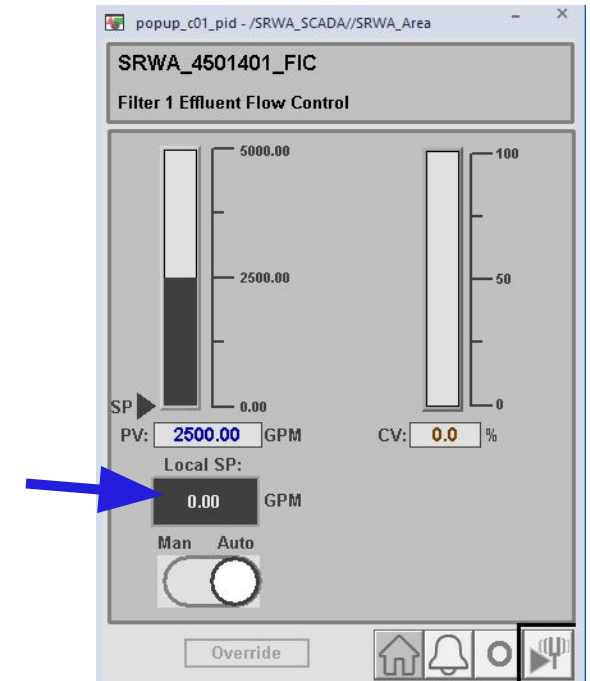
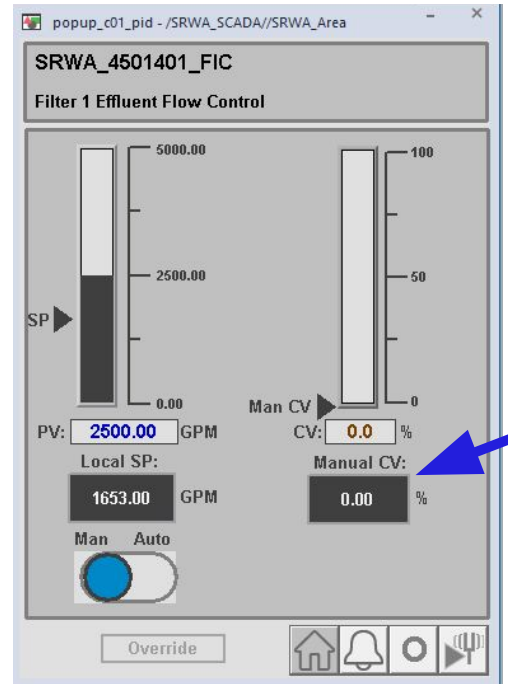
*MV* = Measured Variable

*Max MV* = Maximum Measured Variable

*Min MV* = Minimum Measured Variable

# Manual versus Auto

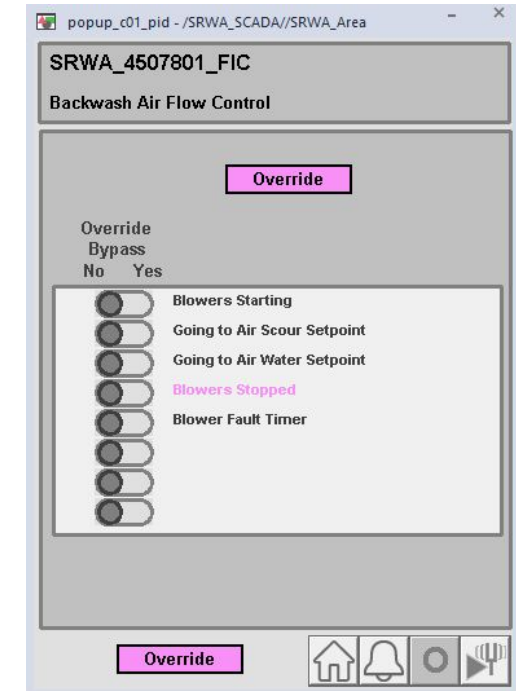
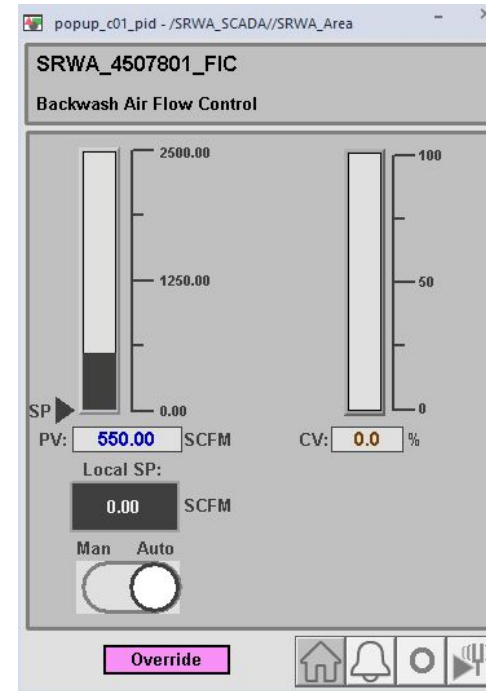
- Manual
  - Allows user to set CV output directly
- Auto
  - CV output set by PID equation to achieve SP





# PID Overrides

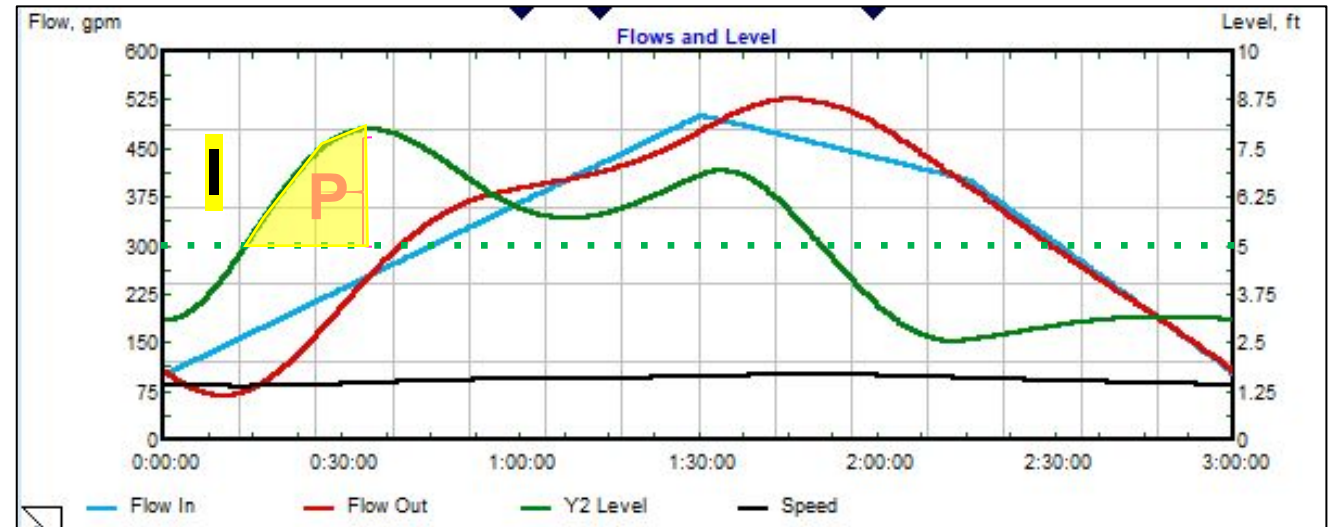
- Used when making a significant process change
  - Ex: increasing or decreasing pump quantity
  - Ex: equipment not running
- CV output set to programmed override value
  - PID equation NOT used determine CV output



# PID Tuning

# PID Tuning

- **Proportional**
  - Acts on the Error
  - Proportional only tuning could end up with constant offset between SP and MV
- **Integral**
  - Acts on the change in Error
- **Derivative**
  - Acts on the rate of change of error
  - Not typically used in water

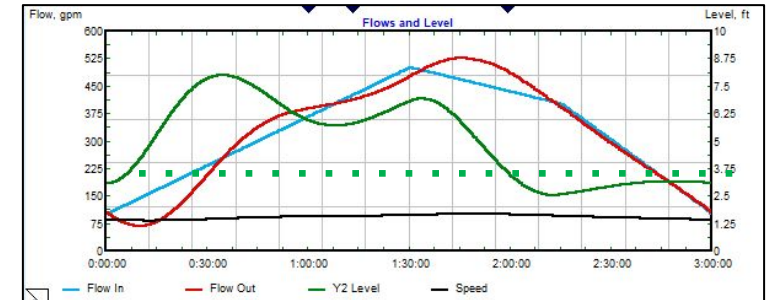


# PID Tuning

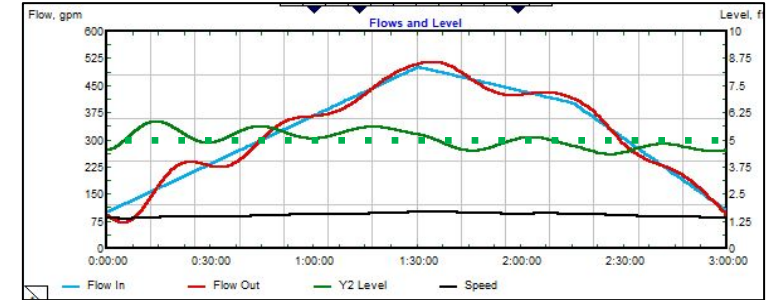
- Make one adjustment at a time, wait until you can see a result, and determine if it is better or worse
- Know the units: will a smaller or larger value result in more integral action
- Write down your tuning changes

$$CV_N = CV_{N-1} + K_C \left( E + \frac{E \Delta t}{T_I} + T_D \frac{\Delta E}{\Delta t} \right) + Bias$$

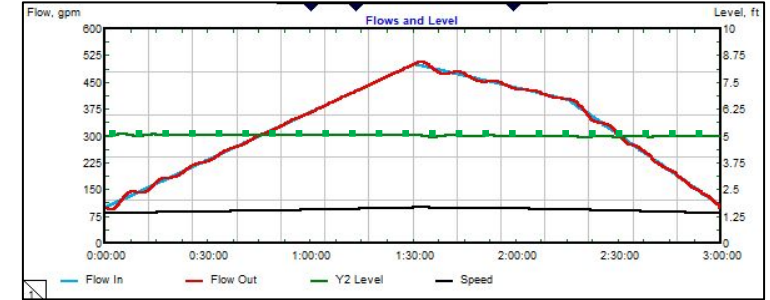
P = -1  
I = 50s



P = -1  
I = 10s



P = -10  
I = 10s



# Questions?

[stephanie.mcgregor@jacobs.com](mailto:stephanie.mcgregor@jacobs.com)



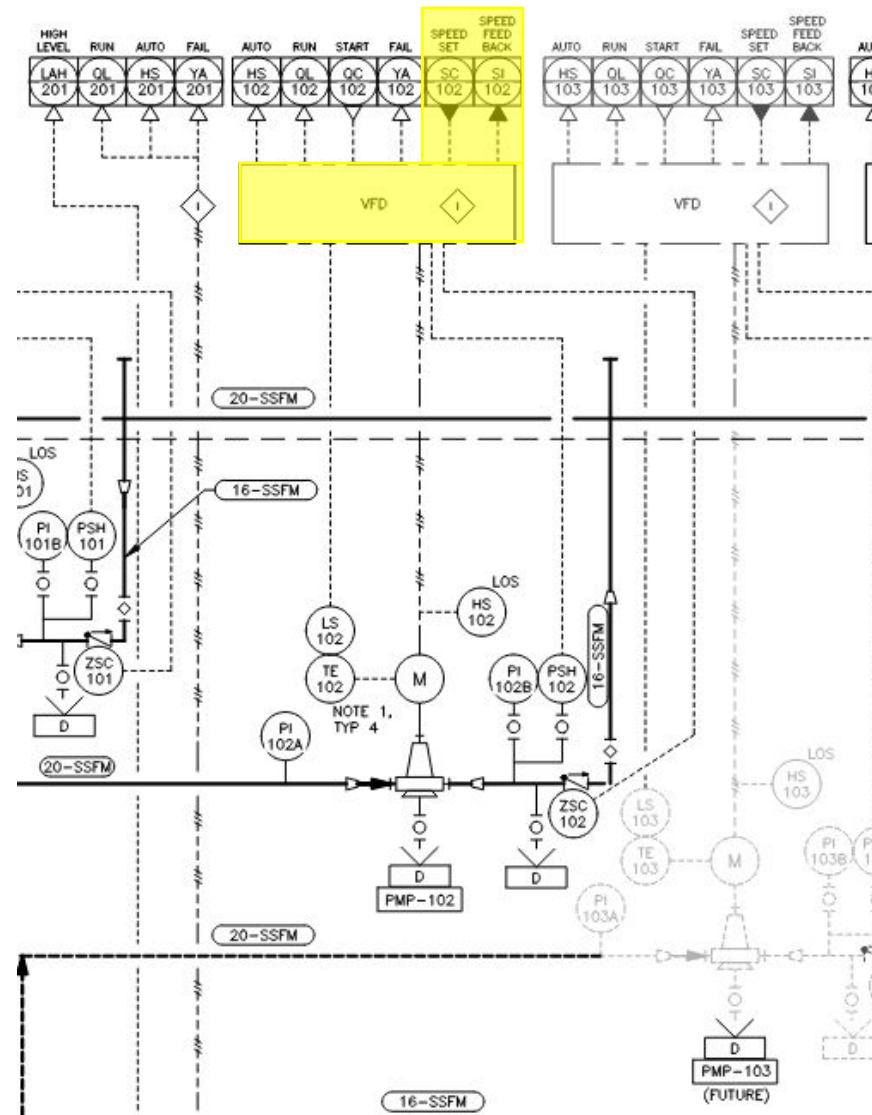
Challenging today.  
Reinventing tomorrow.





# P&IDs

- Pumps
  - Variable Frequency Drives (VFDs)
    - Analog speed command and feedback



# P&IDs

- Pumps
  - Constant Speed (CS)
    - Discrete run command and feedback

